2.4

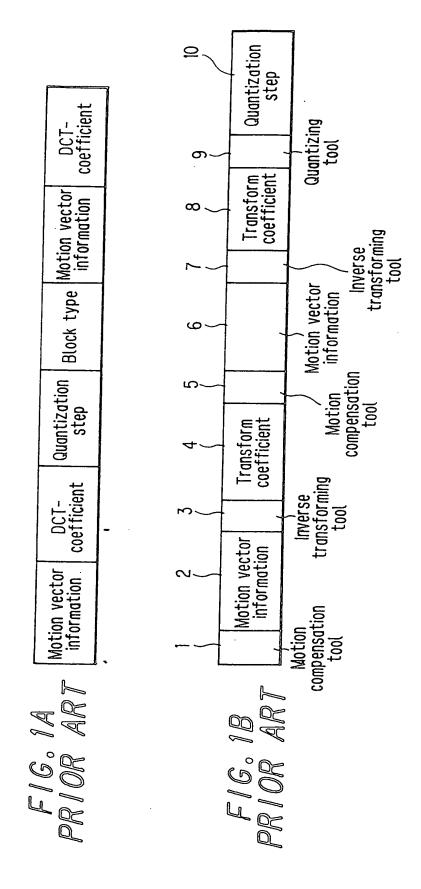
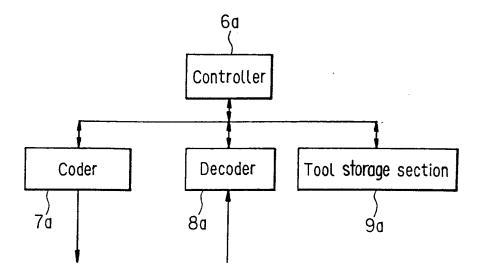
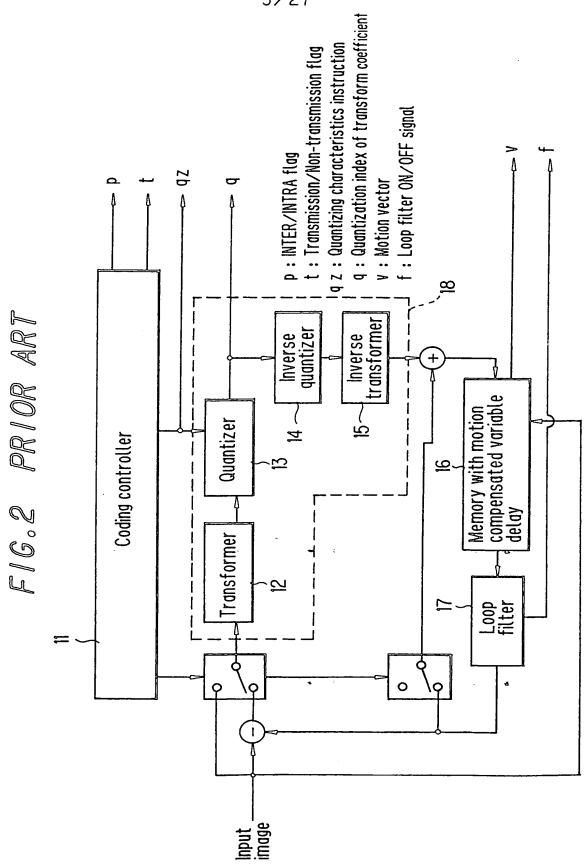
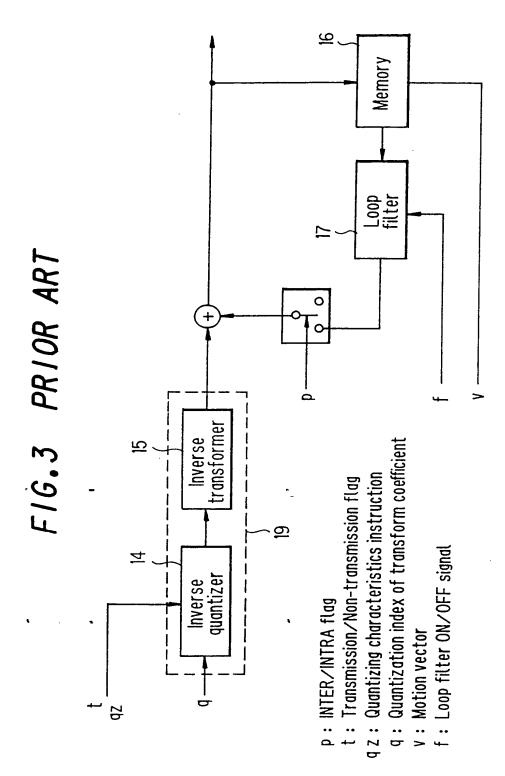


FIG. 1C PRIOR ART



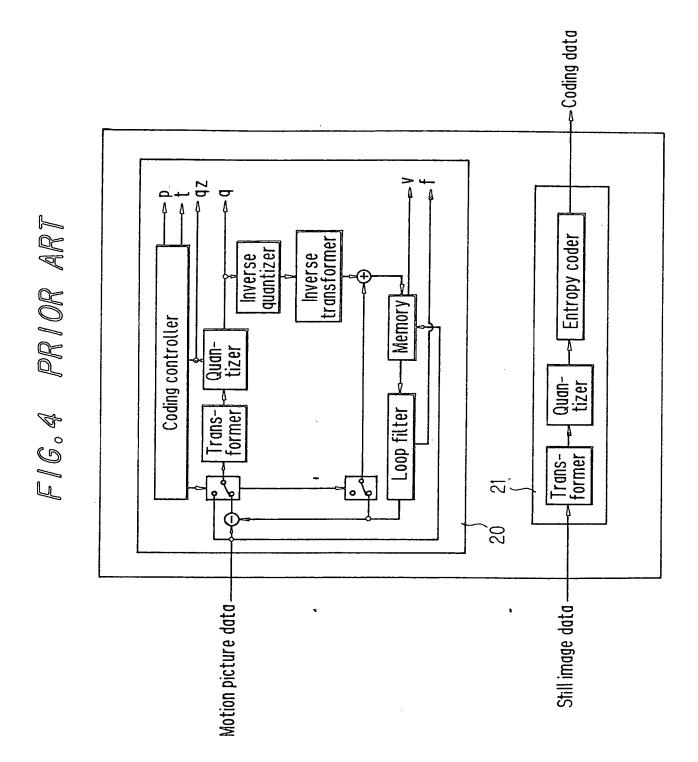


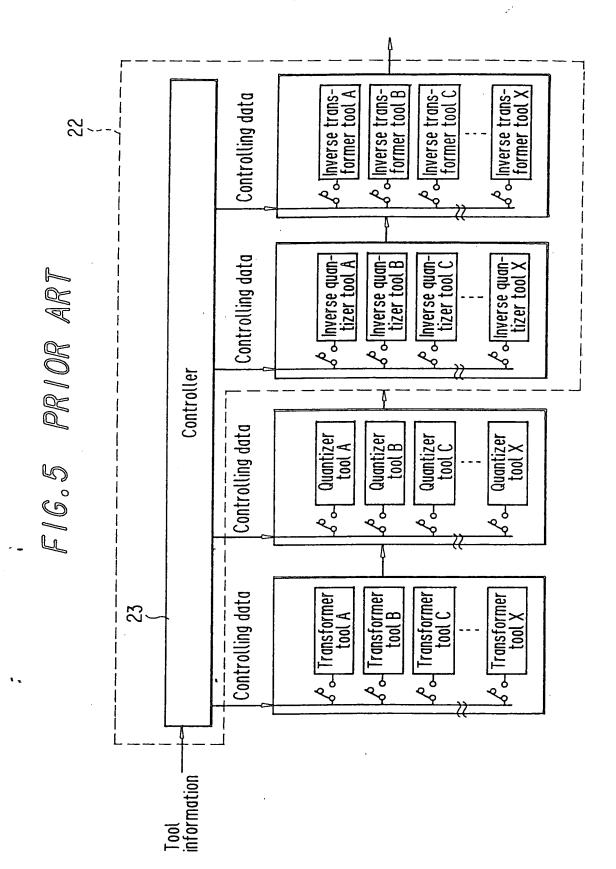
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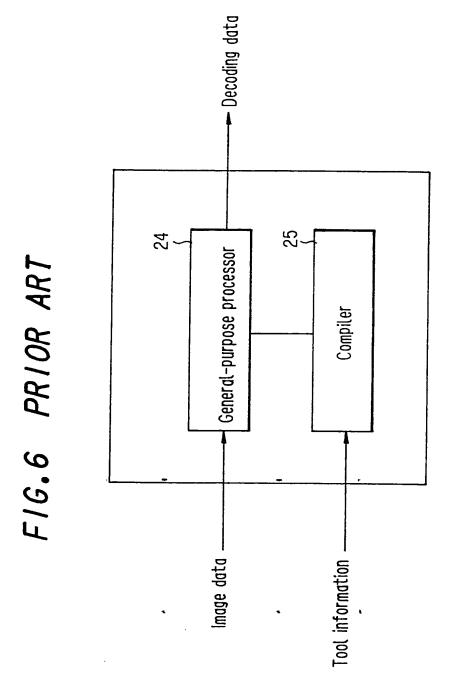
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023

+ 6

FIG. 7A PRIOR ART

FIG. 7B PRIOR ART

- - 4	+ 5
+ 5	+ 5
7 0	+ 0

Sampling per 1/4 pixel

Sampling per 1/2 pixel

Sampling per 1 pixel

022

+8

FIG. 8A PRIOR ART

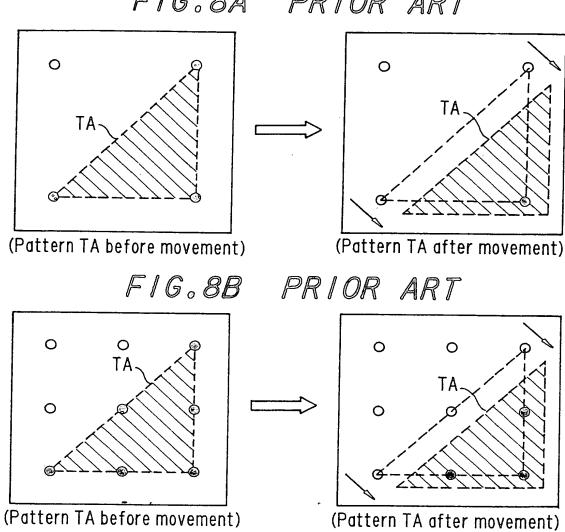
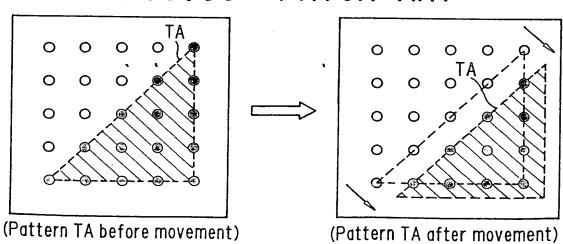


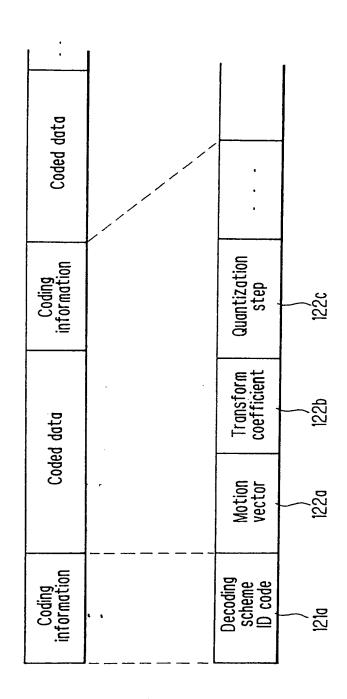
FIG.8C PRIOR ART



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Coded data Quantization Step FIG.9 PRIOR ART 1130 Coding information Motion vector Transform 113b Coded data Quantizing tool 112c Inverse transforming tool Decoding scheme constructing information Motion compensation compensation formation 1<u>2</u>5 Coding information 1120 =

FIG. 10 PRIOR ART



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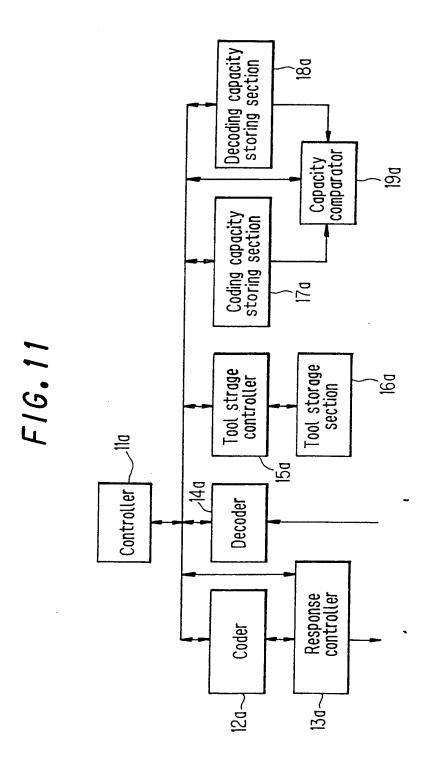
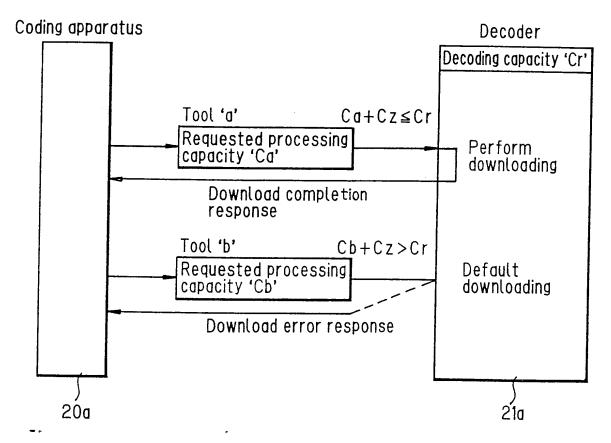


FIG. 12

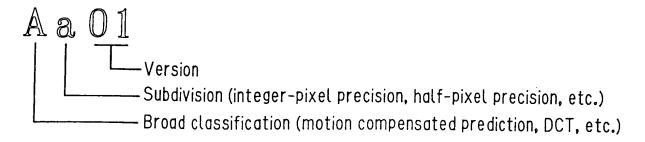


Ca: Coding capacity of tool 'a' Cb: Coding capacity of tool 'b'

Cz: Sum of capacities other than Ca or Cb which constitute algorithm

Cr: Decoding capacity of decoder

F1G.13



F16.14

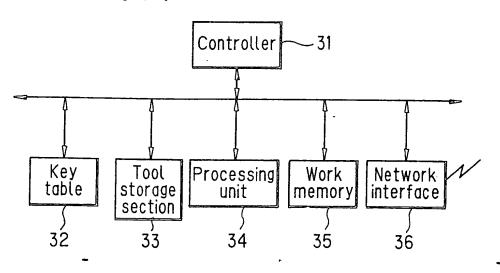
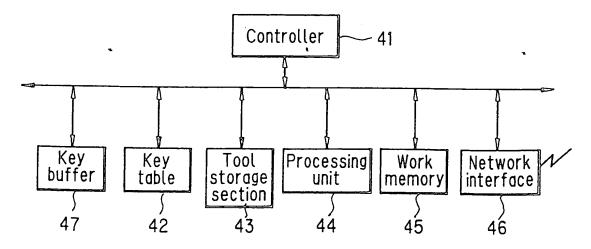
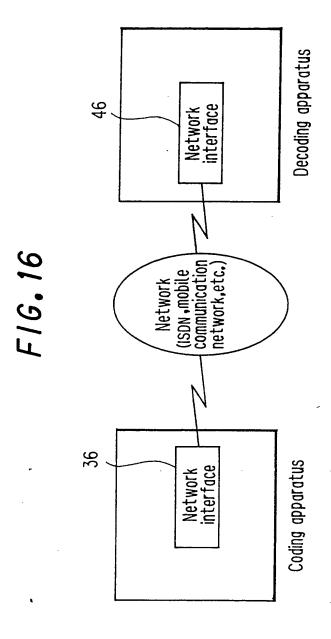


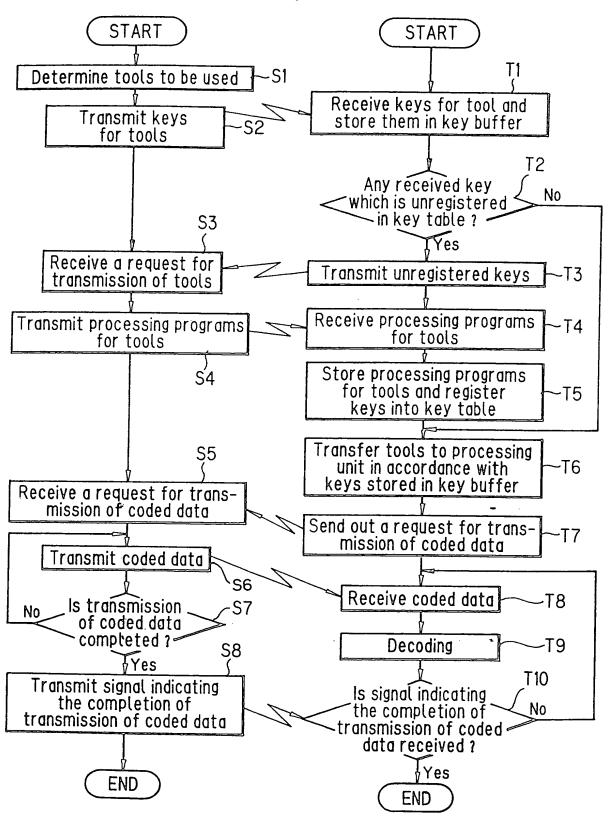
FIG. 15

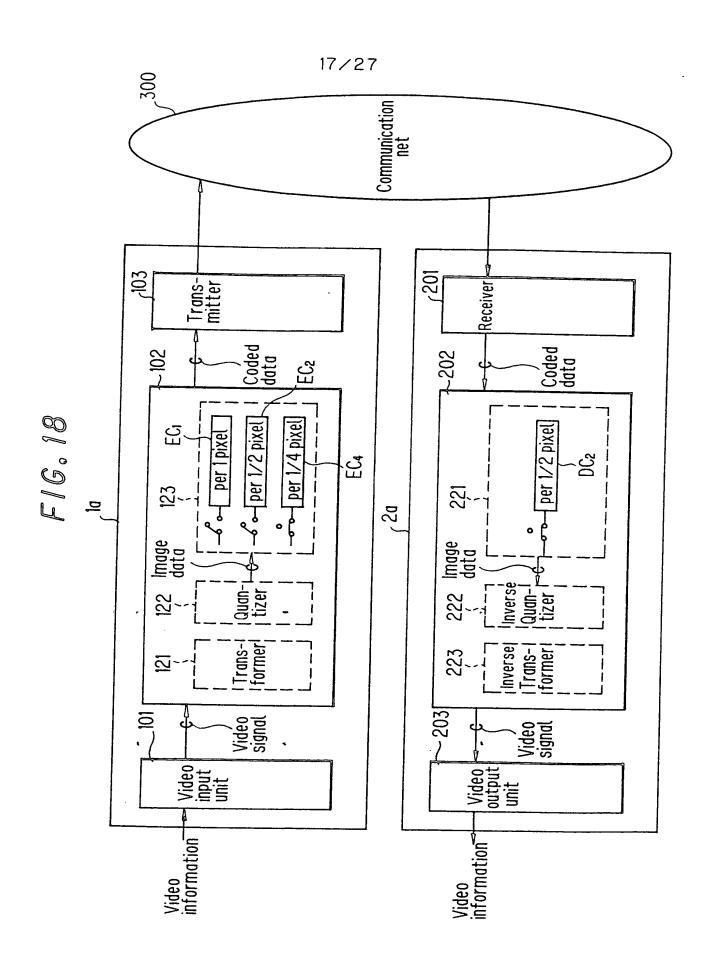


感迹:



F1G.17

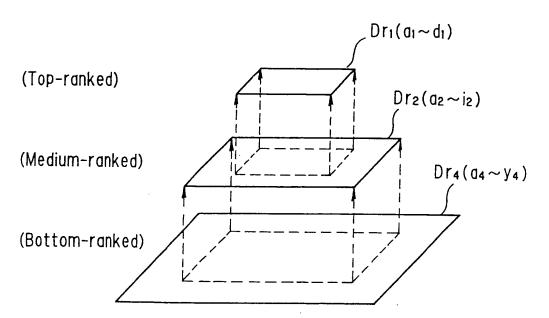




: 35 v.

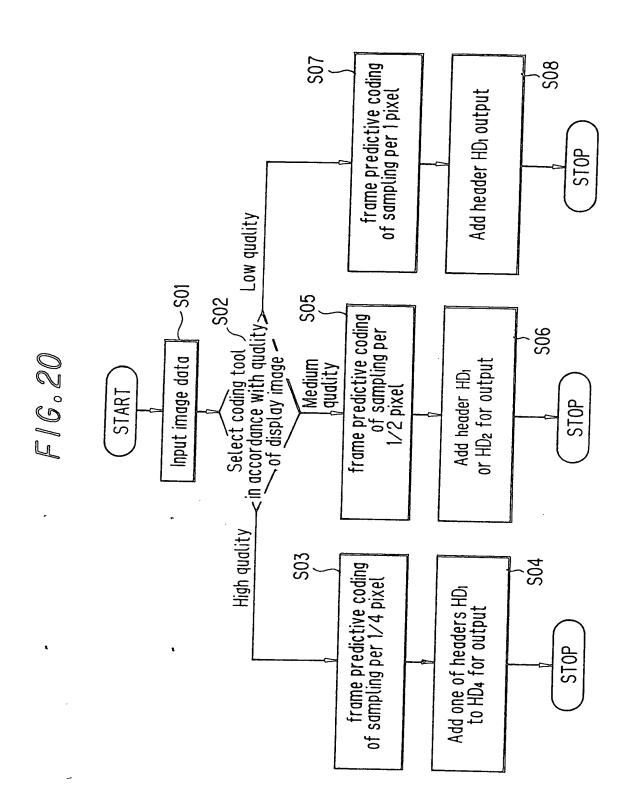
 $\mathbb{Z}p_{q}^{-r(s)}$

FIG. 19



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έψ.; ₂,



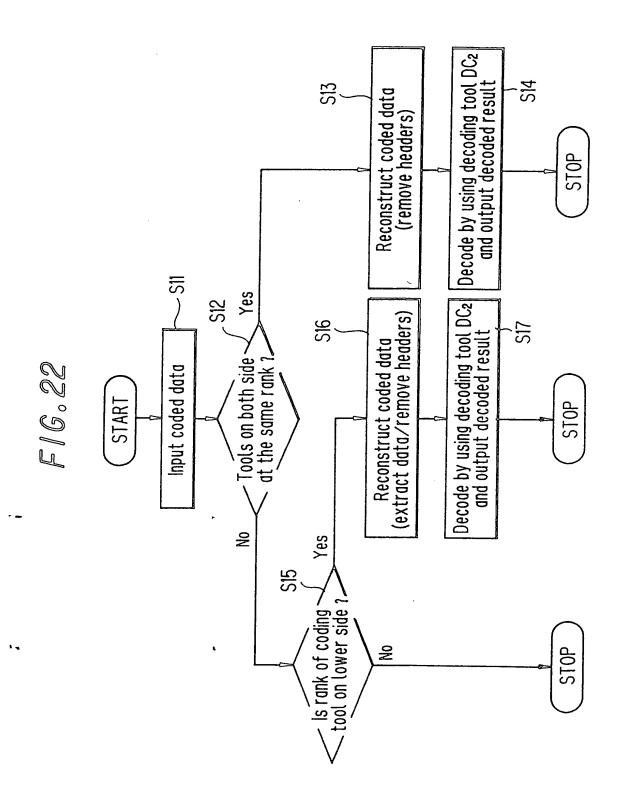
. 띡 춫. <u>ہ</u>. Pixel data stream on the second line 축-ىع ₽ 1 35 주-F16.21A -2 축-83 녚~ Pixel data stream on the first line 굥 宁. స్త 읖 ã 춫. 8 훈-

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1 1

.മ Pixel data stream on the second line .ಲ 2 8 F16.21B <u>4</u>2 축-& 훈 -ম্ব Pixel data stream on the first line 全. ఔ H₂ 23 축 왕 宁-

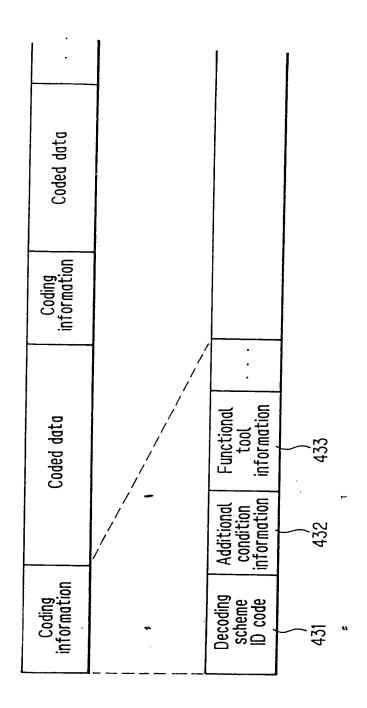
 $V_{i}^{(1)}(z_{j})$



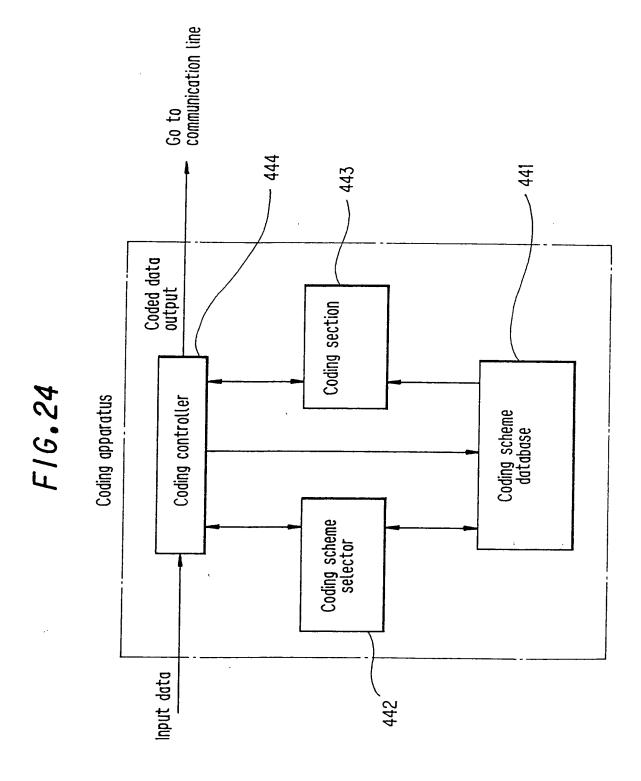
14.35

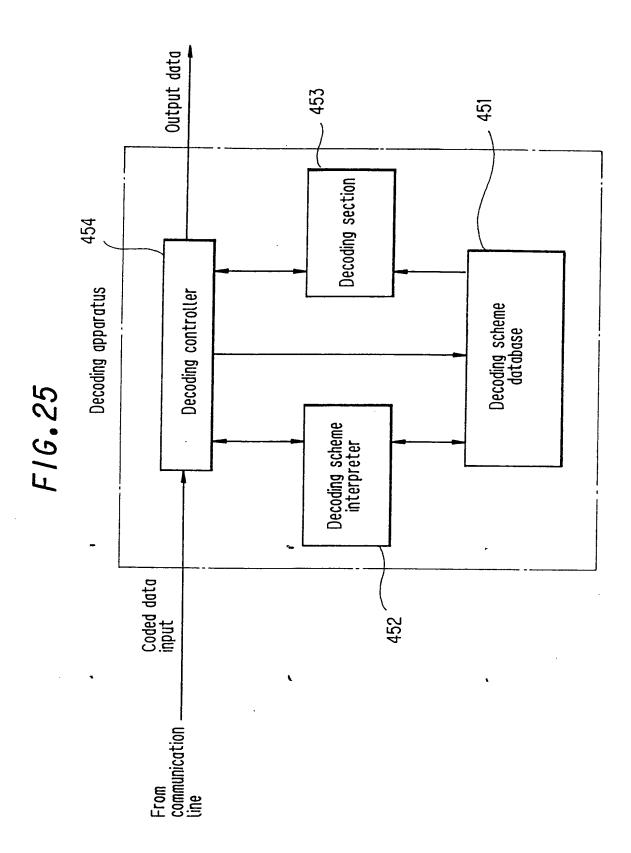
÷.

F16.23

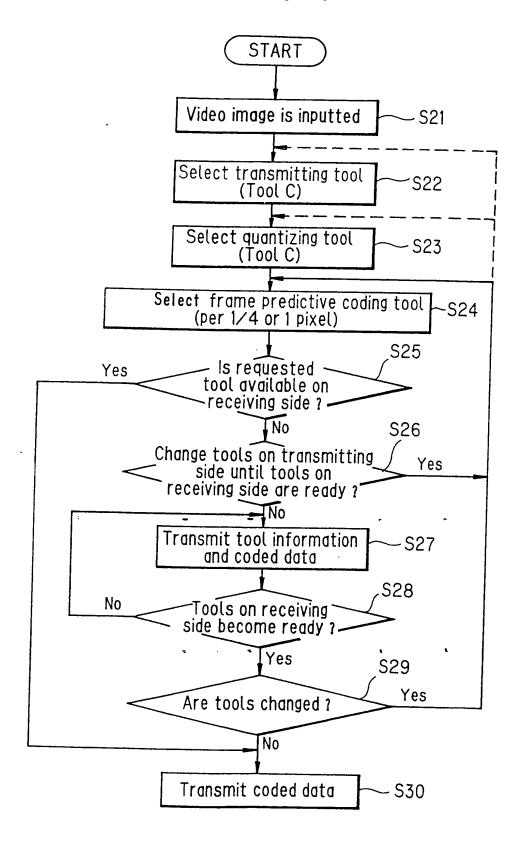


4.5





F1G.27



F16.28

